

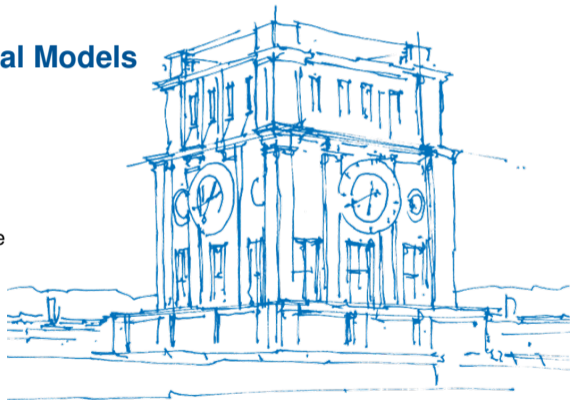
# Learning Linear Non-Gaussian Polytrees Models

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# Problem and setup

## ■ Structure Learning Problem

Learn the DAG  $\mathcal{G}$  of a structural causal model from observational data. Data are  $n$  i.i.d. copies of a  $p$ -dimensional random vector  $X$  satisfying

$$X_i = f_i(X_{\text{pa}(i)}, \varepsilon_i), \quad i \in [p],$$

where the  $\varepsilon_i$  are independent noise terms.

## ■ Challenges

1. The graph  $\mathcal{G}$  can be non identifiable,
2. If  $p$  is large, then usual algorithms are too slow.

## ■ Assumptions

1.  $\mathcal{G}$  is a *Polytree*,
2.  $f_i$  are *Linear*,
3.  $\varepsilon_i$  are *non-Gaussian*.

- The skeleton of the graph is a tree, i.e there are no undirected cycles,

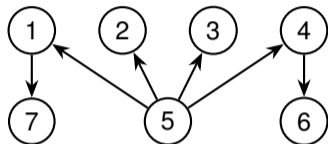


Figure 1 A directed tree<sup>1</sup>

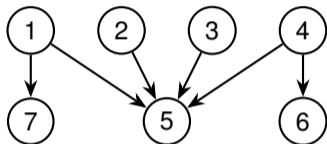


Figure 2 A polytree

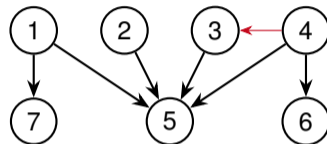


Figure 3 Not a polytree

- Why? The graph can be recovered using any (reasonable) bivariate dependence measures.<sup>2</sup>

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<sup>1</sup>Jakobsen et al. [2022]

<sup>2</sup>Rebane and Pearl [1987]

# Orientation

## ■ Proposed Two-Step Approach

1. Learn the skeleton with Chow-Liu algorithm,
2. Three different orientation schemes.

■ **Orientation Matrix**<sup>3</sup> For a potential edge  $e : i \rightarrow j$  and  $K \in \mathbb{N}$ , define the matrix  $A^{e,K}$  as:

$$\left( c_m^{e,k} \mid 2 \leq m \leq k \leq K \right),$$

where  $c_m^{e,k}$  is the  $k$ th cumulant  $\text{cum}(X_{i_1}, \dots, X_{i_k})$  with  $i_1 = \dots = i_m = i$  and  $i_{m+1} = \dots = i_k = j$ .

## ■ Cumulants

1.  $\text{cum}(X_i) = \mathbb{E}[X_i] = 0$
2.  $\text{cum}(X_{i_1}, X_{i_2}) = \mathbb{E}[X_{i_1} X_{i_2}]$
3.  $\text{cum}(X_{i_1}, X_{i_2}, X_{i_3}) = \mathbb{E}[X_{i_1} X_{i_2} X_{i_3}]$
4.  $\text{cum}(X_{i_1}, X_{i_2}, X_{i_3}, X_{i_4}) = \mathbb{E}[X_{i_1} X_{i_2} X_{i_3} X_{i_4}] - \mathbb{E}[X_{i_1} X_{i_2}] \mathbb{E}[X_{i_3} X_{i_4}] - \mathbb{E}[X_{i_1} X_{i_3}] \mathbb{E}[X_{i_2} X_{i_4}] - \mathbb{E}[X_{i_1} X_{i_4}] \mathbb{E}[X_{i_2} X_{i_3}].$

<sup>3</sup>Améndola et al. [2021]

# Orientation Matrix

■ **Example**( $\mathcal{G} : 1 \rightarrow 2, K = 3$ , zero means) Let  $X_1 = \varepsilon_1$  and  $X_2 = \lambda_{1,2}X_1 + \varepsilon_2$ . Thus:

$$A^{1 \rightarrow 2,3} = \begin{bmatrix} \mathbb{E}(X_1^2) & \mathbb{E}(X_1^3) & \mathbb{E}(X_1^2 X_2) \\ \mathbb{E}(X_1 X_2) & \mathbb{E}(X_1^2 X_2) & \mathbb{E}(X_1 X_2^2) \end{bmatrix} = \begin{bmatrix} \mathbb{E}(\varepsilon_1^2) & \mathbb{E}(\varepsilon_1^3) & \lambda_{1,2} \mathbb{E}(\varepsilon_1^3) \\ \lambda_{1,2} \mathbb{E}(\varepsilon_1^2) & \lambda_{1,2} \mathbb{E}(\varepsilon_1^3) & \lambda_{1,2}^2 \mathbb{E}(\varepsilon_1^3) \end{bmatrix}$$

whereas :

$$A^{2 \rightarrow 1,3} = \begin{bmatrix} \mathbb{E}(X_2^2) & \mathbb{E}(X_2^3) & \mathbb{E}(X_2^2 X_1) \\ \mathbb{E}(X_2 X_1) & \mathbb{E}(X_2^2 X_1) & \mathbb{E}(X_2 X_1^2) \end{bmatrix} = \begin{bmatrix} \lambda_{1,2}^2 \mathbb{E}(\varepsilon_1^2) + \mathbb{E}(\varepsilon_2^2) & \lambda_{1,2}^3 \mathbb{E}(\varepsilon_1^3) + \mathbb{E}(\varepsilon_2^3) & \lambda_{1,2}^2 \mathbb{E}(\varepsilon_1^3) \\ \lambda_{1,2} \mathbb{E}(\varepsilon_1^2) & \lambda_{1,2}^2 \mathbb{E}(\varepsilon_1^3) & \lambda_{1,2} \mathbb{E}(\varepsilon_1^3) \end{bmatrix}.$$

so  $rk(A^{1 \rightarrow 2,3}) = 1$  while  $rk(A^{2 \rightarrow 1,3}) = 2$  (in general).

## ■ Matrix Rank Reveals Orientation

- Let  $e : i \rightarrow j$  be an edge of  $G$ . Then
  - $\text{rank}(A^{i \rightarrow j, K}) = 1$ ,
  - $\text{rank}(A^{j \rightarrow i, K}) = 2$ , in general.
- Suppose the skeleton of  $\mathcal{G}$  contains the subgraph  $i - j - l$  with  $\rho_{i,j}, \rho_{j,l} \neq 0$ . Then the corresponding subgraph of  $G$  is  $i \rightarrow j \leftarrow l$  iff  $\rho_{i,l} = 0$ .

# Orientation Schemes and Consistency

## ■ Orientation Schemes

1. **PO** Orient all the edges independently using lemma 1,
2. **TPO** Orient the first edge using lemma 1, and then use lemma 2 to orient the next edges,
3. **PTO** Learn the the CPDAG first using lemma 2, and then use lemma 1 to orient the remainig edges.

■ **Consistency** Suppose the data are an  $n$ -sample drawn from a distribution in the model given by a polytree  $G$ . Let  $\hat{G}$  be the polytree obtained by applying the orientation scheme **PO** to the (undirected) edge set of

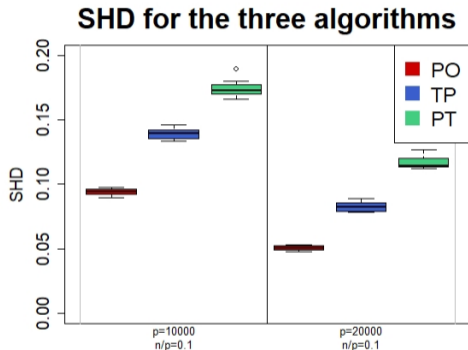
the Chow–Liu tree  $\mathcal{M}(R_n)$ . There is a set of constants  $\{\delta', M_K, L\}$  such that  $\hat{G} = G$  with probability greater than

$$1 - 4B(K)(p-1) \exp \left\{ -\frac{2}{LK^2\sqrt{M_K}} (\delta'\sqrt{n})^{\frac{1}{K}} \right\} + \\ - \frac{3p(p-1)}{2} \exp \left\{ -\frac{1}{2L\sqrt{M_2}} \left( \frac{\lambda\gamma\sqrt{n}}{2+\lambda} \right)^{\frac{1}{2}} \right\},$$

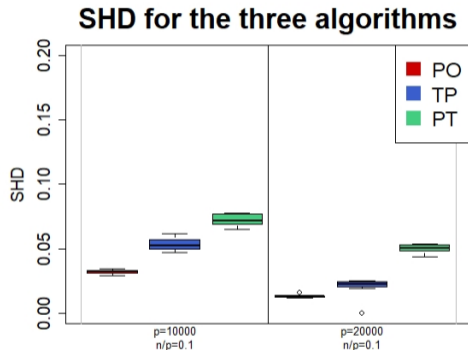
for all  $n$  greater than:

$$\max \left\{ \frac{e^2(2+\lambda)^2(4L^2\sqrt{M_2})^4}{\lambda^2\gamma^2}, \frac{e^2(LK^2\sqrt{M_K})^{2K}}{\delta'^2} \right\},$$

where  $p$  is the size of the tree and  $n$  is the sample size.



**Figure 4** Structural Hamming distance on simulated polytrees,  $p = 10000, 20000$ ,  $n/p = 0.1$  and  $\varepsilon_i$  drawn from a gamma distribution



**Figure 5** Structural Hamming distance on simulated polytrees,  $p = 10000, 20000$ ,  $n/p = 0.1$  and  $\varepsilon_i$  drawn from a uniform distribution

## Future Work?

1. Other identifiable settings?
2. How to avoid Chow–Liu?
3. Which tree structures are the most difficult to learn?<sup>4</sup>
4. What happens when the graph is not a tree?<sup>5</sup>

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<sup>4</sup>Tan et al. [2009]

<sup>5</sup>Acid and de Campos [1994], Dasgupta [1999], Grüttemeier et al. [2021]



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